(19) Europäisches Patentamt
European Patent Office
Office européen des brevets

(11) EP 1 162 162 A1

(12) EUROPEAN PATENT APPLICATION

published in accordance with Art. 158(3) EPC

(43) Date of publication:
12.12.2001 Bulletin 2001/50

(21) Application number: **00981733.9**

(22) Date of filing: **14.12.2000**

(51) Int Cl.[7]: **B65G 47/86**

(86) International application number:
PCT/JP00/08879

(87) International publication number:
WO 01/44086 (21.06.2001 Gazette 2001/25)

(84) Designated Contracting States:
AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU MC NL PT SE TR
Designated Extension States:
AL LT LV MK RO SI

(30) Priority: **16.12.1999 JP 35729499**

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(54) METHOD AND DEVICE FOR TRANSPORTATION

(57) A transfer apparatus **10** includes crank arms **22** each of which is pivotally attached to a driving wheel **21**, link levers **23** each of which has its one end pin-linked to the tip of the crank arm **22**, and revolving sections **30** each of which is pin-linked to the other end of the link lever **23** and held at a distance from the rotation axis **210** of the driving wheel **21**, wherein: the crank arm **22** is provided with a velocity-changing cam roller **223** protruding therefrom at a position spaced apart from the pivot center thereof; the velocity-changing cam roller **223** is guided while being engaged with the velocity-changing cam groove **44** which is formed to be eccentric to the rotation axis **210** of the driving wheel **21**, whereby the tip of the crank arm **22** swings during one complete rotation of the driving wheel **21**; and, as a result, the angular velocity of the link lever **23** linked to the tip of the crank arm **22** and the revolving section **30** periodically increases/decreases with respect to the angular velocity of the driving wheel **21**.

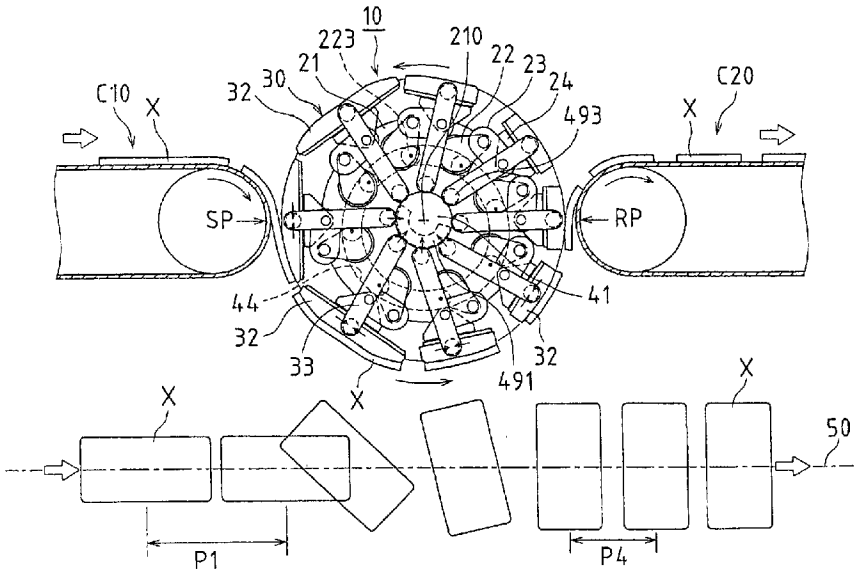

FIG. 2

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Description

TECHNICAL FIELD

[0001] The present invention relates to a transfer method for increasing or decreasing the transfer velocity of a workpiece (including a material) when the workpiece moving on a transfer line is handed over to another transfer line, and a transfer apparatus having the accelerating/decelerating function.

BACKGROUND ART

[0002] Japanese Patent No. 2580493 discloses an apparatus for cutting sanitary goods, and increasing the transfer pitch of the cut sanitary goods. specifically, the die cutter roll for cutting and transferring the sanitary goods hands over the sanitary goods to a transfer roll that rotates at a higher velocity than the circumferential velocity of the die cutter roll, whereby the transfer pitch of the sanitary goods on the transfer surface of the transfer roll is greater than the transfer pitch thereof on the transfer surface of the die cutter roll.

[0003] Japanese Laid-Open Patent Publication No. 63-317576 discloses a technique of cutting an elastic tape by a rotating drum, turning the cut elastic tape pieces on the rotating drum by 90° with respect to the transfer direction, and attaching the elastic tape pieces to an adherend sheet being transferred by an adherend sheet transfer apparatus. The circumferential velocity of the rotating drum is higher than the circumferential velocity of an elongation roller for feeding the elastic tape to the rotating drum, and the elastic tape, which is a continuous member, is gradually elongated while being in contact with the surface of the rotating drum, thereby increasing the interval between the cut elastic tape pieces.

[0004] Japanese Laid-Open Patent Publication No. 57-102427 discloses a transfer apparatus for transferring an elongate stick-shaped item such as a cigarette in a direction perpendicular to the axial direction thereof. This transfer apparatus holds each stick-shaped item in a housing having a semicircular cross section, and changes the transfer pitch of the stick-shaped items held on a linking conveyer, which is disposed between two conveyers , while the linking conveyer moves about halfway around.

[0005] United States Patent No. 5,025,910 discloses a technique for turning a vacuum pickup shoe by 90°.

[0006] However, when transferring a soft workpiece which has a length or width such as sanitary goods, for example, by using the conventional techniques described above, the workpiece is likely to be wrinkled when it is handed over between rotating members such as rolls and drums, thereby failing to sufficiently satisfy the requirement of transferring an item stably and at a high velocity. The present invention provides a transfer method and a transfer apparatus capable of satisfying such a requirement.

DISCLOSURE OF THE INVENTION

[0007] A transfer method of the present invention is a transfer method for transferring a workpiece from a preceding stage to a subsequent stage by using a transfer apparatus including at least one transfer section capable of revolving around a rotation axis, the method including: a pickup step, wherein in order for the transfer section to pick up the workpiece transferred by the preceding stage at a first transfer velocity, the transfer section moves at a pickup velocity substantially equal to the first transfer velocity in a pickup area having a width; a velocity-changing step of changing the transfer velocity of the transfer section while the transfer section is holding the workpiece which has been picked up; and a hand-over step, wherein in order to transfer the workpiece at a second transfer velocity by the subsequent stage, the transfer section moves at a hand-over velocity substantially equal to the second transfer velocity in a hand-over area having a width, wherein the pickup velocity and the hand-over velocity are different from each other.

[0008] A transfer apparatus of the present invention is a transfer apparatus, including at least one transfer section capable of revolving around a rotation axis, and a velocity-changing section for changing a transfer velocity of the transfer section, wherein: in order for the transfer section to pick up a workpiece transferred at a first transfer velocity, the transfer section holds the workpiece while moving at a pickup velocity substantially equal to the first transfer velocity in a pickup area having a width; the velocity-changing section changes the transfer velocity of the transfer section holding the workpiece; in order to transfer the workpiece at a second transfer velocity outside the transfer apparatus, the transfer section moves at a hand-over velocity substantially equal to the second transfer velocity in a hand-over area having a width; and the pickup velocity and the hand-over velocity are different from each other.

[0009] These configurations will be described with reference to the basic conceptual diagram of FIG. **1.**

[0010] A transfer apparatus **1** provided between a preceding stage **C1** and a subsequent stage **C2** picks up a workpiece **X** to a transfer section **3** from the preceding stage **C1,** and hands over the workpiece **X** to the subsequent stage **C2** after changing the transfer velocity of the workpiece **X** which has been picked up. Each of the preceding stage **C1** and the subsequent stage **C2** includes a drum, a conveyer, or any other transfer device, for moving the workpiece **X** at predetermined transfer velocities, and the configuration of each stage is not limited to any particular configuration.

[0011] The workpiece **X** has a predetermined length with respect to the transfer direction and a predetermined width. The predetermined length is a length that is less than or equal to the longitudinal dimension of the

workpiece holding surface of the transfer section **3**, and the predetermined width is a width that is less than or equal to the widthwise dimension of the holding surface. With the configuration illustrated in FIG. **1**, the workpiece **X** is transferred in the longitudinal direction in the preceding stage **C1**, and then the direction thereof is changed in the transfer plane (the revolving plane of the transfer section **3**) by means of a direction-changing section **5** provided in the transfer apparatus **1,** after which the workpiece **X** is transferred in the widthwise direction in the subsequent stage **C2.** Note that the direction of the workpiece **X** may not be changed, or may be changed from the widthwise direction to the longitudinal direction.

[0012] As for the direction-changing section **5,** the direction-changing section **5** may have a motor, for example, so that it is capable of turning the transfer section **3**. However, in order to allow a rotating member **4** to rotate at a high velocity, it is preferred that the direction-changing section **5** is provided by using a direction-changing cam groove as will be described later. This is because it is then possible to reduce the weight of the rotating member **4**. The direction-changing section **5** may alternatively be a rail such as a monorail instead of a direction-changing cam groove **48** as illustrated in FIG. **9**. The driving force for turning the transfer section **3** may be supplied from a power source for rotating the rotating member **4**.

[0013] The transfer apparatus **1** includes at least one transfer section **3** for picking up and holding the workpiece **X.** The transfer section **3** revolves around a rotation axis **11.** In FIG. **1,** the transfer section **3 (3a)** immediately before picking up the workpiece **X** from the preceding stage **C1** is shown in a solid line, and the transfer section **3** (**3b**) immediately after picking up the workpiece **X** is shown in a two-dot chain line. The transfer section **3** (**3c**) immediately before handing over the workpiece **X** to the subsequent stage **C2** is shown in a solid line, and the transfer section **3 (3d)** immediately after handing over the workpiece **X** is shown in a two-dot chain line.

[0014] The transfer section **3** picks up the workpiece **X**, which is supplied from the preceding stage **C1** at a first transfer velocity (transfer velocity **V1**), in a pickup area adjoining the preceding stage **C1** and having a width. At least in this pickup area, the transfer velocity of the transfer plane is maintained at a substantially constant pickup velocity **V2.** The transfer section **3** being located in the pickup area means that a predetermined point **PL** of the transfer section **3** is in the pickup area. In the example illustrated in FIG. **1,** the predetermined point **PL** is located at the longitudinal center of the holding surface of the transfer section **3**. The pickup velocity **V2** is set to be substantially equal to the transfer velocity **V1** of the preceding stage **C1.**

[0015] Herein, the pickup area is an area that is defined by an angle **R1** about the rotation axis **11** in FIG. **1.** The pickup area includes a pickup point **SP** at which the transfer section **3** comes closest to the preceding stage **C1.** Where the predetermined point **PL** is at the longitudinal center of the holding surface of the transfer section 3, it is preferred that the pickup area extends substantially by an angle **R1**/2 forward and backward with respect to the transfer direction about a line extending between the pickup point **SP** and the rotation axis **11.** However, this may not be the case depending upon the workpiece **X** to be transferred and the configuration of the transfer section **3.** The degree of the angel **R1** depends upon the length of the workpiece **X** along the transfer direction in the vicinity of the pickup point **SP.**

[0016] As the transfer section **3** picks up the workpiece **X** in the pickup area, the transfer apparatus **1** changes via a velocity-changing section **2** the transfer velocity of the transfer section **3** from the pickup velocity **V2** to a hand-over velocity **V3**. The velocity-changing section **2** is provided on the rotating member **4** rotating about the rotation axis **11**, and is capable of reciprocating over a predetermined area of the rotating member **4**. For example, the velocity-changing section **2** may have a motor so that it can move with respect to the rotating member **4.** However, in order to allow the rotating member **4** to rotate at a high velocity, it is preferred that the velocity-changing section **2** is provided by using a velocity-changing guide that is provided on the rotating member **4** to be eccentric to the rotation axis **11**, whereby the circumferential velocity of the transfer section **3** at the revolving surface thereof is changed, as will be described later. This is because it is then possible to reduce the weight of the rotating member **4**. The velocity-changing guide may be a groove cam or a rail such as amonorail. Basically, such a velocity-changing guide has a generally circular shape or a generally elliptical shape eccentric to the rotation axis **11**, and may include a straight portion and/or a curved portion. By using such a velocity-changing guide, the transfer section **3** can be moved substantially at a constant velocity for a period of time, as will be described later. The driving force for moving the velocity-changing section **2** along the velocity-changing guide may be supplied from a power source for rotating the rotating member **4.**

[0017] The transfer section **3** releases the workpiece **X** in a hand-over area adjoining the subsequent stage **C2** and having a width. The released workpiece **X** is handed over to the subsequent stage **C2,** and transferred at a second transfer velocity (transfer velocity **V4**). At least in this hand-over area, the transfer velocity of the transfer plane is maintained at a substantially constant hand-over velocity **V3.** The transfer section **3** being located in the hand-over area means that a predetermined point **PS** of the transfer section **3** is in the hand-over area. In the example illustrated in FIG. **1**, the predetermined point **PS** is located at the widthwise center of the holding surface of the transfer section **3**. The predetermined point **PL** and the predetermined point **PS** are different from each other because the transfer section **3** is turned. The hand-over velocity **V3** is set to be

substantially equal to the transfer velocity **V4** of the subsequent stage **C2.**

[0018] The hand-over area is an area that is defined by an angle **R2** about the rotation axis **11** in FIG. **1**. The hand-over area includes a hand-over point **RP** at which the transfer section **3** comes closest to the subsequent stage **C2**. Where the predetermined point **PS** is at the widthwise center of the holding surface of the transfer section **3**, it is preferred that the hand-over area extends substantially by an angle **R2**/2 forward and backward with respect to the transfer direction about a line extending between the hand-over point **RP** and the rotation axis **11.** However, this may not be the case depending upon the workpiece **X** to be transferred and the configuration of the transfer section **3.** The degree of the angel **R2** depends upon the length of the workpiece **X** along the transfer direction in the vicinity of the hand-over point **RP.**

[0019] As described above, one transfer method and one transfer apparatus of the present invention are configured so that the workpiece **X** is picked up by the transfer section **3** in a pickup area having a width at the pickup velocity **V2** which is substantially equal to the transfer velocity **V1** of the preceding stage **C1,** the transfer velocity of the transfer section **3** having picked up the workpiece **X** is changed to the hand-over velocity **V3,** and then the workpiece **X** is handed over to the subsequent stage **C2** in a hand-over area having a width at the hand-over velocity **V3** which is substantially equal to the transfer velocity **V4** of the subsequent stage **C2**. Therefore, the transfer pitch of the workpiece **X** changes as the transfer velocity is changed.

[0020] Where the transfer velocity **V4** of the subsequent stage **C2** is higher than the transfer velocity **V1** of the preceding stage **C1,** a transfer pitch **P4** of the workpiece **X,** which has been handed over to the subsequent stage **C2,** is wider than a transfer pitch **P1** in the preceding stage **C1.** Conversely, where the transfer velocity **V4** of the subsequent stage **C2** is lower than the transfer velocity **V1** of the preceding stage **C1,** the transfer pitch **P4** of the workpiece **X**, which has been handed over to the subsequent stage **C2**, is narrower than the transfer pitch **P1** in the preceding stage **C1**. Then, as the predetermined point **PS** of the transfer section **3** moves away from the hand-over area, the velocity of the transfer section **3** changes from the hand-over velocity **V3** to the pickup velocity **V2** before the predetermined point **PL** of the transfer section **3** enters the pickup area.

[0021] In this way, the transfer velocity and the transfer pitch of the workpiece **X** are changed while the workpiece **X** is handed over from the preceding stage **C1** to the subsequent stage **C2,** whereby the workpiece **X** can be efficiently transferred in a manner suitable for the process particulars, the process purposes, etc.

[0022] Moreover, a transfer apparatus of the present invention includes a vacuum adjustment section for attracting the workpiece **X** onto the transfer section **3** by way of vacuum suction at least while the transfer section **3** is in the pickup area, and stopping the vacuum suction so as to release the workpiece **X** from the transfer section 3 at least while the transfer section **3** is in the hand-over area. With this configuration, even when the workpiece **X** is by nature soft and unstable, the workpiece **X** can be smoothly handed over at a high speed without wrinkling the workpiece **X.**

[0023] Furthermore, in the transfer apparatus of the present invention, a holding surface of the transfer section **3** for holding the workpiece **X** is a convex surface so that the transfer section **3** can reliably pick up and hand over the workpiece **X.**

[0024] It is desirable that at the pickup point **SP,** the holding surface of the transfer section **3** approaches the workpiece **X** on the preceding stage **C1** in a continuous manner in a direction from the front edge to the rear edge thereof along the transfer direction. For this purpose, the holding surface of the transfer section **3** is provided with an inclination such that the vicinity of the central portion thereof is raised, with respect to the front edge and the rear edge, along the normal line extending from the rotation axis **11** through the vicinity of the central portion of the transfer section **3.** More specifically, it is preferred that the holding surface of the transfer section **3** coincides with the revolving plane of the transfer section **3** as the transfer section **3** at the pickup point **SP** is viewed from a direction along the extension of the rotation axis **11**.

[0025] Similarly, it is desirable that at the hand-over point **RP,** the holding surface of the transfer section **3** moves theworkpiece **X** held on the holding surface to continuously approach the transfer plane of the subsequent stage **C2** in a direction from the front edge to the rear edge thereof along the transfer direction. For this purpose, the holding surface of the transfer section **3** is provided with an inclination such that the vicinity of the central portion thereof is raised, with respect to the front edge and the rear edge, along the normal line extending from the rotation axis **11** through the vicinity of the central portion of the transfer section **3.** More specifically, it is preferred that the holding surface of the transfer section **3** coincides with the revolving plane of the transfer section **3** as the transfer section **3** at the hand-over point **RP** is viewed from a direction along the extension of the rotation axis **11**.

[0026] Thus, it is preferred that the shape of the holding surface of the transfer section **3** satisfies the above-described two requirements at the pickup point **SP** and the hand-over point **RP.** However, it is not easy to actually produce a curved surface that satisfies such two requirements. Therefore, in the longitudinal direction, only the edges of the holding surface of the transfer section 3 may be formed each as a spherical surface with the normal line mentioned above being the radius thereof.

[0027] The holding surface may be formed by using a spherical surface with the normal line mentioned above being the radius thereof, a curved surface approximating to the spherical surface, a flat surface, or a

surface made up of a combination thereof. In a case where the holding surface side of the transfer section **3** is made of an elastic material whose shape changes upon application of a pressure, the shape of the transfer section **3** may be any shape other than those described above.

[0028] The type of the workpiece **X** for use in the present invention may include, for example, a product or a semi-finished product of a sanitary napkin, a disposable diaper, disposable underpants, a bandage, other sanitary goods, and similar worn articles in general. Moreover, the form of the workpiece **X** may include a single sheet or a laminate of sheets layered on one another. The sheet may be liquid absorptive, liquid permeable, liquid semi-permeable, or liquid impermeable. Moreover, the sheet may be woven fabric or non-woven fabric. While the transfer method and the transfer apparatus of the present invention are particularly suitable for transferring the workpieces **X** of the types and forms as described above, the type and form of the workpieces **X** are not limited to those described above.

BRIEF DESCRIPTION OF THE DRAWINGS

[0029]

FIG. **1** is a diagram illustrating the basic concept of a transfer method and a transfer apparatus of the present invention.

FIG. **2** is a diagram illustrating an example of how a workpiece is transferred by a transfer apparatus according to an embodiment of the present invention.

FIG. **3** is a general perspective view illustrating the transfer apparatus.

FIG. **4** is an exploded perspective view illustrating a general configuration of the transfer apparatus.

FIG. **5** is a partially-cross-sectional side view illustrating a side view of the transfer apparatus as viewed from a direction perpendicular to the rotation axis thereof, while also illustrating a cross section thereof taken along a plane including the rotation axis.

FIG. **6** is a front view illustrating an operation of a link mechanism for accelerating/decelerating the velocity of a revolving section.

FIG. **7** is a partial front view illustrating the link mechanism as viewed from a direction along the extension of the rotation axis.

FIG. **8** is a partial cross-sectional view illustrating a cross section of the link mechanism taken along a plane including the rotation axis.

FIG. **9** is a partial side view illustrating a cylindrical cam mechanism for turning an attracting member of a revolving section.

BEST MODE FOR CARRYING OUT THE INVENTION

[0030] An embodiment of the present invention will now be described with reference to the drawings.

[0031] FIG. **2** to FIG. **4** illustrate the operation and general configuration of a transfer apparatus **10** according to an embodiment of the present invention. The transfer apparatus **10** includes a generally cylindrical rotor rotating about a rotation axis **210**, and is provided between a preceding stage conveyer **C10** and a subsequent stage conveyer **C20.** Each of the illustrated preceding stage conveyer **C10** and subsequent stage conveyer **C20** carries a light-weight and soft workpiece **X** (e.g., sanitary goods such as a sanitary napkin) on an air-permeable transfer belt, and continuously transfers the workpiece **X** while attracting the workpiece **X** by way of vacuum suction, etc. The member for attracting the workpiece **X** is not limited to vacuum suction, but may alternatively be any other suction member such as an electrostatic charge, for example. The transfer member of each of the preceding stage and the subsequent stage may be a drum or any other device instead of a conveyer.

[0032] In this embodiment, the workpiece **X** is transferred in the longitudinal direction on the preceding stage conveyer **C10,** and is attracted onto the transfer apparatus **10** at the pickup point **SP.** Then, after the transfer apparatus **10** turns the direction of theworkpiece **X** by about 90 ° with respect to the transfer direction, the workpiece **X** is re-mounted onto the subsequent stage conveyer C20 at the hand-over point **RP.** Then, the workpiece **X** is transferred on the subsequent stage conveyer **C20** in the widthwise direction.

[0033] Inthis embodiment, the transfervelocity of the subsequent stage conveyer **C20** is set to be lower than the transfer velocity of the preceding stage conveyer **C10,** and the subsequent stage transfer pitch **P4** at which the workpieces **X** are arranged in its widthwise direction is narrower than the preceding stage transfer pitch **P1** at which the workpieces **X** are arranged in its longitudinal direction. The transfer apparatus **10** is configured so as to pick up the workpiece **X** at the predetermined pickup point **SP** at a high circumferential velocity according to the transfer velocity of the preceding stage conveyer **C10,** and to hand over the workpiece **X** at the predetermined hand-over point **RP** at a low circumferential velocity according to the transfer velocity of the subsequent stage conveyer **C20**.

[0034] As illustrated in FIG. **4**, the mechanism of the transfer apparatus **10** can be generally divided into the following sections: a velocity-changing section **20** having a generally disc-shaped driving wheel **21**; at least one (eight in this example) revolving section **30** being attached to the driving wheel **21** along the periphery thereof and revolving with the driving wheel **21**; and a generally cylindrical base body section **40** for rotatably/revolvably supporting the velocity-changing section **20** and the revolving sections **30**.

[0035] The velocity-changing section **20** includes the driving wheel **21**, crank arms **22**, link levers **23**, and linking blocks **24**. As illustrated in FIG. **5**, the driving wheel **21** is linked to one end of a driving shaft **41**, which is inserted through the center of the base body section **40**. A driving gear **42** is attached to the other end of the driving shaft **41.** The driving shaft **41** and the driving wheel **21** rotate at a constant velocity about the rotation axis **210** while obtaining a driving force from a motor (not shown), etc., via the driving gear **42**.

[0036] As illustrated in FIG. **6** to FIG. **8**, the same number of crank arms **22** as the revolving sections **30** are attached to the driving wheel **21** near the periphery thereof and are disposed at regular intervals. Each crank arm **22** includes a disc-shaped substrate section **221**, an arm section **222** extending from the surface of the substrate section **221** in the direction away from the substrate section **221,** and a velocity-changing cam roller **223** protruding on the reverse side of the substrate section **221.** The substrate section **221** is attached via an annular bearing **212** to a crank arm support hole **211** formed in a circular shape in the driving wheel **21**. Thus, the crank arms **22** are held with respect to the driving wheel **21** so that they can be turned independently of one another. The velocity-changing cam roller **223** is provided at a position spaced apart from a pivot center **220** of the crank arm **22** by a distance, and moves along a velocity-changing cam groove **44** to be described later.

[0037] The arm section **222** of each crank arm **22** is pivotally linked to one end of the link lever **23** via a pin linking section **231.** The other end of the link lever **23** is pivotally linked to the linking block **24** via a pin linking section **232.** One end of the revolving section **30** is fixed to the linking block **24.**

[0038] The pin linking section **231** may be any linking structure as long as it pivotally links the crank arm **22** and the link lever **23** to each other. Similarly, the pin linking section **232** may be any linking structure as long as it pivotally links the link lever **23** and the linking block **24** to each other.

[0039] As illustrated in FIG. **4** to FIG. **5**, the base body section **40** includes a generally cylindrical casing **401**, the driving shaft **41** and the driving gear **42** described above, a flange **45** formed at one end of the casing **401**, lock plates **46** attached to the casing **401** along the periphery thereof, a cylindrical cam **47** provided along the periphery of the casing **401**, a vacuum shaft **49** inserted through the driving shaft **41,** etc. The casing **401,** the cylindrical cam **47**, the driving shaft **41**, the driving gear **42** and the vacuum shaft **49** are coaxial with the rotation axis **210**.

[0040] The driving shaft **41** has a hollow cylindrical shape and is rotatably attached to the casing **401** via a bearing **43.** The vacuum shaft **49** inserted through the driving shaft **41** is rotatably held with respect to the driving shaft **41** via a bearing **492**. Therefore, even when the driving shaft **41** rotates, the casing **401** and the vacuum shaft **49** do not rotate.

[0041] The flange **45** is provided with the velocity-changing cam groove **44**. The velocity-changing cam roller **223** of the crank arm **22** in the velocity-changing section **20** described above is placed in the velocity-changing cam groove **44**, and is held so that it can move along the velocity-changing cam groove **44**. Thus, the velocity-changing cam groove **44** serves as a velocity-changing guide that restricts the movement of the velocity-changing cam roller **223.** While it is preferred that the shape of the velocity-changing cam groove **44** is a generally circular shape or a generally elliptical shape, it may alternatively be composed of a group of linear segments and/or non-linear segments. In this embodiment, the velocity-changing cam groove **44** is formed in a generally elliptical shape that is eccentric to the rotation axis **210**, as illustrated in FIG. **6.**

[0042] The direction-changing cam groove **48** is provided around the periphery of the cylindrical cam **47**. The direction-changing cam groove **48** is formed so as to run all the way around the side surface of the cylindrical cam **47** while being displaced in the direction of the generatrix of the cylindrical cam **47** (the direction parallel to the rotation axis **210**). The cylindrical cam **47** serves as a direction-changing guide that restricts the movement of a direction-changing cam roller **322** to be described later.

[0043] Each revolving section **30** includes an elongate, flat, and box-shaped drive box **31**, and an attracting member **32** pivotally held at one end of the drive box **31**. The drive box **31** is linked to the link lever **23** via the linking block **24**, and is linked to the lock plate **46** attached to the base body section **40** along the periphery thereof, as illustrated in FIG. **5**. The lock plates **46** are generally annular members, attached to the casing **401** of the base body section **40** via bearings **461**, and held so that they can rotate around the casing **40** independently of one another. Each lock plate **46** is provided with an arm **462** protruding from a position of the lock plate **46** along its circumference, and the drive box **31** is linked to the arm **462**. Therefore, the drive box **31** revolves around the base body section **40** being entailed by the rotation of the driving wheel **21,** while keeping a constant distance from the rotation axis **210** with the longitudinal direction thereof being parallel to the rotation axis **210**.

[0044] The attracting member **32** is a member for attracting/releasing the workpiece **X,** and corresponds to the transfer section **3** in the basic concept of the present invention illustrated in FIG. **1**. The surface of the attracting member **32** serves as the holding surface for the workpiece **X.** The attracting member **32** has a cylindrical pivot shaft **321** generally at the center thereof. The pivot shaft **321** is pivotally held, via a bearing **312**, by a cylindrical support section **311** provided in the drive box **31**. The pivot shaft **321** is held in a direction perpendicular to the revolving plane of the revolving drive box **31**, i.e., a direction toward the rotation axis **210**. Moreover, the attracting member **32** is provided with the direction-changing cam roller **322**. The direction-changing cam

roller **322** is provided so as to protrude on the side of the base body section **40** at a position spaced apart from the pivot center of the pivot shaft **321** by a distance. The direction-changing cam roller **322** moves along the direction-changing cam groove **48** formed in the cylindrical cam **47** of the base body section **40**, as illustrated in FIG. **9**. The direction-changing cam groove **48** is formed so as to run all the way around the side surface of the cylindrical cam **47** while being displaced in the direction of the generatrix of the cylindrical cam **47**. Therefore, the attracting member **32** moves with periodic pivoting within a angle range according to the position of the direction-changing cam roller **322** along the direction-changing cam groove **48**. As illustrated in FIG. **2**, in this embodiment, the attracting member **32** has its longitudinal direction aligned with the revolving direction at the pickup point **SP**, and the attracting member **32** is turned by about 90° while the revolving section **30** moves halfway around, so that at the hand-over point **RP,** the widthwise direction thereof is aligned with the revolving direction.

[0045] The drive box **31** and the attracting member **32** are hollow and are communicated to each other as illustrated in FIG. **5.** The surface of the attracting member **32** is provided with a plurality of small apertures **323** that reach the inside of the attracting member **32**. It is preferred that the small apertures **323** are provided at least in the vicinity of the front edge of the holding surface of the attracting member **32** in the revolving direction. This is because it is easier to prevent the workpiece **X** from being wrinkled upon picking up the workpiece **X**, when the workpiece **X** starts to be attracted by a portion of the holding surface of the attracting member **32** that first reaches the pickup point **SP**.

[0046] A hose **33** curved in a U shape is connected to one end of each of the drive boxes **31**. The hose **33** is connected to a vacuum communication aperture **493** formed in the vicinity of the junction between the driving wheel **21** and the driving shaft **41**.

[0047] The vacuum communication aperture **493** meets a vacuum adjustment port **491** provided at one end of the vacuum shaft **49**. The vacuum adjustment port **491** is formed by, for example, providing an opening in the vacuum shaft **49** having a cylindrical shape at a position along its circumference. Thus, the vacuum communication aperture **493**, which rotates along with the driving wheel **21**, is communicated to, and disconnected from, the vacuum adjustment port **491** depending upon its position in rotation. When the vacuum communication aperture **493** is communicated to the vacuum adjustment port **491**, the air is sucked from the other end of the vacuum shaft **49,** as indicated by arrows in FIG. **5,** to depressurize the inside of the suction path extending from the hose **33** to the attracting member **32** via the drive box **31**, thereby attracting the workpiece **X** onto the attracting member **32.** Conversely, when the vacuum communication aperture **493** and the vacuum adjustment port **491** are disconnected from each other, the internal pressure of the suction path is recovered to about the atmospheric pressure, thereby releasing the workpiece **X** from the attracting member **32.** In this embodiment, the vacuum adjustment port **491** is formed so that the suction path is established when the attracting member **32** comes close to the pickup point **SP** and disconnected when the attracting member **32** comes close to the hand-over point **RP,** as illustrated in FIG. **2.** With the vacuum adjustment section having the vacuum adjustment port **491** as described above, the timing of attracting and releasing the workpiece **X** is controlled.

[0048] The specific manner of controlling the timing of establishing or disconnecting the suction path may be modified as necessary as long as the path is established at least at the pickup point **SP** and disconnected at least at the hand-over point **RP**.

[0049] With the transfer apparatus **10** of this embodiment, the transfer velocity is changed as follows.

[0050] As illustrated in FIG. **6**, the driving wheel **21** is provided with a plurality of crank arms **22**, which are disposed at regular intervals (regular angular intervals with respect to the rotation axis **210**). The interval between the crank arms **22** is constant, and the pivot center **220** of each of the crank arms **22** rotates at the same angular velocity as the driving wheel **21**.

[0051] However, the velocity-changing cam roller **223** is provided for each crank arm **22** at a position spaced apart from the pivot center **220** thereof, and the velocity-changing cam roller **223** moves along the velocity-changing cam groove **44** formed in the flange **45** of the base body section **40.** The velocity-changing cam groove **44** is formed to be eccentric to the center of the driving wheel **21** (the rotation axis **210**), and does not move. Therefore, the distance from the rotation axis **210** to the velocity-changing cam roller **223** periodically increases/decreases depending upon the positions of the velocity-changing cam roller **223** and the velocity-changing cam groove **44**. Thus, the crank arm **22** periodically pivots within a angle range, whereby the tip of the crank arm **22** periodically swings. Specifically, the tip of the crank arm **22** is displaced forwardly in the transfer direction with respect to the pivot center **220** of the crank arm **22** in the first range (generally the lower half in FIG. **6**), and backwardly in the second range (generally the upper half in FIG. **6**). Then, the link lever **23** pin-linked to the tip of the crank arm **22** and the linking block **24** pin-linked to the link lever **23** are also displaced forwardly or backwardly being entailed by the swinging of the tip of the crank arm **22.** Moreover, since the distance between the pivot center **220** of the crank arm **22** and the linking block **24** changes as the crank arm **22** swings, the interval between adjacent linking blocks **24** also changes. As a result, the angular velocity of the revolving section **30** linked to the linking block **24**, and the interval thereof with respect to the adjacent revolving sections **30**, change.

[0052] Since each revolving section **30** is individually linked to the lock plate **46** (see FIG. **4,** FIG. **5**), the dis-

tance from the rotation axis **210** to each revolving section **30** is always constant, and the orientation of the revolving section **30** with respect to the transfer plane is also held constant.

[0053] While the revolving section **30** smoothly revolves around the base body section **40**, the revolving section **30** is accelerated in an accelerating area so that the revolving section **30** is at a pickup velocity in the pickup area where it picks up the workpiece **X,** thereby increasing the interval between adjacent transfer sections **30,** and the revolving section **30** is decelerated in a decelerating area so that the revolving section **30** is at a hand-over velocity in the hand-over area where it hands over the workpiece **X,** thereby decreasing the interval between adjacent transfer sections **30.** Thus, the workpiece **X** is picked up in the pickup area from the preceding stage conveyer **C10** whose transfer velocity is high, and the workpiece **X** is handed over in the hand-over area to the subsequent stage conveyer **C20** whose transfer velocity is low. The arrangement of the pickup area, the decelerating area, the hand-over area and the accelerating area may be adjusted as necessary by changing the shape of the velocity-changing cam groove **44**, the position of the velocity-changing cam roller **223** in the crank arm **22**, etc.

[0054] As described above, the transfer apparatus **10** of this embodiment is characterized in that: the revolving section **30** is rotatably held with respect to the rotation axis **210** while it is held at a constant distance from the rotation axis **210**; the crank arm **22** pivotally held with respect to the driving wheel **21** and the link lever **23** whose one end is pin-linked to the tip of the crank arm **22** are provided in the vicinity of the periphery of the driving wheel **21**, the other end of the link lever **23** being pin-linked to the revolving section **30**; the crank arm **22** is provided with the velocity-changing cam roller **223** protruding therefrom at a position spaced apart from the pivot center **220** thereof; the velocity-changing cam roller **223** moves along the velocity-changing cam groove **44** formed to be eccentric to the driving wheel **21**, whereby the tip of the crank arm **22** swings with respect to the driving wheel **21** during one complete rotation of the driving wheel **21**; and, as a result, the angular velocity of the revolving section **30** linked to the crank arm **22** via the link lever **23** periodically increases/decreases with respect to the angular velocity of the driving wheel **21**.

[0055] By changing the circumferential velocity of the revolving section **30** in the pickup area (the pickup velocity) from the circumferential velocity of the revolving section **30** in the hand-over area (the hand-over velocity) as described above, the transfer velocity can be smoothly decreased/increased between the preceding stage and the subsequent stage having different transfer velocities. Therefore, even when the workpiece **X** is a soft and light-weight item, the workpiece **X** can be handed over appropriately, continuously, and at a high velocity, thereby contributing to an increase in the efficiency of the manufacturing process. Moreover, since a driving force that gives the driving wheel **21** a constant-velocity rotation is sufficient as the driving force for driving the transfer apparatus **10**, it is not necessary to control the driving force with complicated controller.

[0056] Furthermore, in addition to the above-described configuration, the transfer apparatus **10** is characterized in that: the revolving section **30** is provided with the attracting member **32** capable of pivoting in the transfer plane; the attracting member **32** is provided with the direction-changing cam roller **322** protruding therefrom at a position spaced apart from the pivot center thereof; the cylindrical cam **47** coaxial with the rotation axis **210** is provided inside the locus of revolution of the revolving section **30**; the direction-changing cam groove **48** is formed around the side surface of the cylindrical cam **47** while being displaced in the direction of the generatrix thereof; and the direction-changing cam roller **322** is guided along the direction-changing cam groove **48**, whereby the direction of the attracting member **32** with respect to the transfer direction periodically changes depending upon the position of the revolving section **30**.

[0057] With such a configuration, it is possible to pivot the attracting member **32** in the transfer plane and to change the direction of the workpiece **X** with respect to the transfer direction while the workpiece **X** is handed over from the preceding stage to the subsequent stage. Thus, it is possible to transfer the workpiece **X** in a direction suitable for the process particulars and/or the process purposes of the preceding and subsequent stages .

[0058] The above embodiment has been described with respect to the particular manner of transfer, in which the workpiece **X** is transferred along the longitudinal direction on the preceding stage conveyer **C10** where the velocity is high, and then the workpiece **X** is decelerated and the direction thereof is changed by the transfer apparatus **10,** after which it is transferred along the widthwise direction on the subsequent stage conveyer **C20** where the velocity is low. However, the present invention is not limited to this, and the transfer apparatus **10** can be also used to address other situations where, for example, the velocity of the preceding stage conveyer **C10** is low and the velocity of the subsequent stage conveyer **C20** is high, by reversing the position and timing of accelerating/decelerating the revolving section **30** from that described above. In such a case, a more complicated shape than a generally circular shape or a generally elliptical shape may be employed for the velocity-changing cam groove **44** so as to achieve more complicated accelerating/decelerating timings. Moreover, it is optional to change the direction of the workpiece **X** with respect to the transfer direction, and the angle by which the workpiece **X** is turned is not limited to 90°, but one may freely set it by changing the shape of the cylindrical cam **47.** Moreover, the present invention can be applied to apparatuses in which the unit for attracting/releasing

the workpiece **X** is provided by using a mechanism other than a vacuum mechanism.

[0059] Where the attracting member **32** illustrated in FIG. **6** and FIG. **9** is formed in a shape indicated by a broken line, not a solid line, the workpiece **X** can be handed over to the subsequent stage while it is shifted from a center line **50** of the transfer direction illustrated in FIG. **2**. In the attracting member **32** having a shape indicated by the broken line, the pivot center of the attracting member **32** and the center of the holding surface thereof are offset from each other, thereby shifting the workpiece **X** from the center line **50** of the transfer direction only to one side. Note however that the workpieces **X** may be placed in a staggered arrangement with respect to the center line **50,** for example, by individually changing the shape of the holding surface of the attracting member **32** and/or the positional relationship between the holding surface and the object-turning cam roller **322**.

INDUSTRIAL APPLICABILITY

[0060] With the transfer method or the transfer apparatus of the present invention, a workpiece having a predetermined length can be picked up in a pickup area at a pickup velocity that is substantially equal to the transfer velocity of the preceding stage, and can be handed over in a hand-over area to the subsequent stage at a hand-over velocity that is substantially equal to the transfer velocity of the subsequent stage. Therefore, it is unlikely that the workpiece is wrinkled or elongated more than necessary upon picking up and releasing the workpiece. Particularly, the present invention is such that the transfer velocity of the workpiece does not substantially change between a point in time immediately before and a point in time immediately after picking up and releasing the workpiece, and thus the present invention is suitable for transfer at a high speed.

[0061] Moreover, with the transfer method or the transfer apparatus of the present invention, since the pickup velocity and the hand-over velocity are different from each other, the transfer pitch of the workpieces can be changed. Therefore, in a case where, for example, a continuous material is cut into workpieces of a predetermined length, while there is substantially no spacing between workpieces immediately after the cutting, the transfer pitch of the workpieces can be increased by handing over the workpieces to another stage by using the transfer method or the transfer apparatus of the present invention. In a case where, for example, a web having an adhesive member is transferred in the subsequent stage, workpieces can be arranged on the web at an intended interval.

[0062] Thus, the present invention makes it possible to manufacture sanitary goods or other worn articles, for example, at a high speed. Moreover, the present invention makes it possible to prevent troubles that can be encountered while transferring workpieces and/or to reduce the possible loss of the material being processed during a transfer step, thereby improving the efficiency in transferring and processing the workpieces.

Claims

1. A transfer method for transferring a workpiece from a preceding stage to a subsequent stage by using a transfer apparatus comprising at least one transfer section capable of revolving around a rotation axis, the method comprising:

   a pickup step, wherein in order for the transfer section to pick up the workpiece transferred by the preceding stage at a first transfer velocity, the transfer section moves at a pickup velocity substantially equal to the first transfer velocity in a pickup area having a width;
   a velocity-changing step of changing the transfer velocity of the transfer section while the transfer section is holding the workpiece which has been picked up; and
   a hand-over step, wherein in order to transfer the workpiece at a second transfer velocity by the subsequent stage, the transfer section moves at a hand-over velocity substantially equal to the second transfer velocity in a hand-over area having a width,
   wherein the pickup velocity and the hand-over velocity are different from each other.

2. A transfer method according to claim 1, comprising a direction-changing step of changing a direction of the workpiece by pivoting the transfer section in a transfer plane between the pickup step and the hand-over step.

3. A transfer method according to claim 1, wherein where the hand-over velocity is higher than the pick-up velocity, a transfer pitch of workpieces in the hand-over area is increased to be greater than a transfer pitch of the workpieces in the pickup area.

4. A transfer method according to claim 1, wherein where the hand-over velocity is lower than the pick-up velocity, a transfer pitch of workpieces in the hand-over area is decreased to be less than a transfer pitch of the workpieces in the pickup area.

5. A transfer method according to claim 1, wherein the workpiece is one of a product and a semi-finished product of sanitary goods or a similar worn article, a single sheet, and a laminate of sheets.

6. A transfer apparatus, comprising at least one transfer section capable of revolving around a rotation axis, and a velocity-changing section for changing

a transfer velocity of the transfer section, wherein:

in order for the transfer section to pick up a workpiece transferred at a first transfer velocity, the transfer section holds the workpiece while moving at a pickup velocity substantially equal to the first transfer velocity in a pickup area having a width;
the velocity-changing section changes the transfer velocity of the transfer section holding the workpiece;
in order to transfer the workpiece at a second transfer velocity outside the transfer apparatus , the transfer section moves at a hand-over velocity substantially equal to the second transfer velocity in a hand-over area having a width; and
the pickup velocity and the hand-over velocity are different from each other.

7. A transfer apparatus according to claim 6, wherein the velocity-changing section changes the transfer velocity of the transfer section by using a velocity-changing guide provided to be eccentric to the rotation axis.

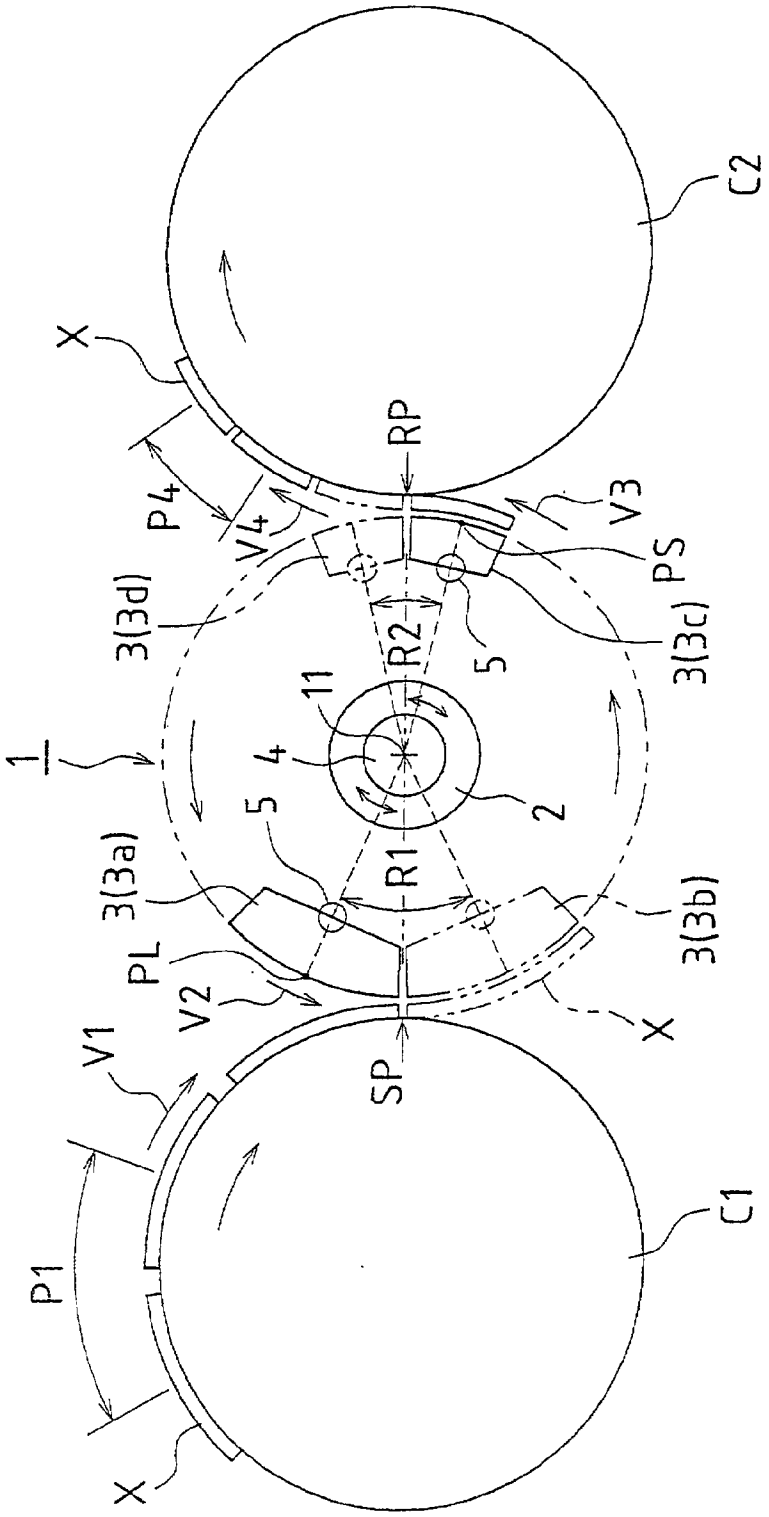
8. A transfer apparatus according to claim 6, comprising a direction-changing section for changing a direction of the workpiece by pivoting the transfer section in a transfer plane while the transfer section moves from the pickup area to the hand-over area.

9. A transfer apparatus according to claim 6, comprising a vacuum adjustment section for attracting the workpiece onto the transfer section by way of vacuum suction at least while the transfer section is in the pickup area, and stopping the vacuum suction so as to release the workpiece from the transfer section at least while the transfer section is in the hand-over area.

10. A transfer apparatus according to claim 6, wherein a holding surface of the transfer section for holding the workpiece is a convex surface.

11. A transfer apparatus according to claim 6, wherein a holding surface of the transfer section for holding the workpiece is provided with an inclination such that a vicinity of a central portion of the holding surface is higher than a front edge and a rear edge of the holding surface with respect to a transfer direction, whereby in the pickup area, the holding surface approaches the workpiece from the preceding stage in a direction from the front edge to the rear edge thereof along the transfer direction.

12. A transfer apparatus according to claim 6, wherein a holding surface of the transfer section for holding the workpiece is provided with an inclination such that a vicinity of a central portion of the holding surface is higher than a front edge and a rear edge of the holding surface with respect to a transfer direction, whereby in the hand-over area, the holding surface moves the workpiece to approach to a portion of the subsequent stage where the subsequent stage receives the workpiece being handed over in a direction from the front edge to the rear edge thereof along the transfer direction.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RP
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P1
X

FIG. 1

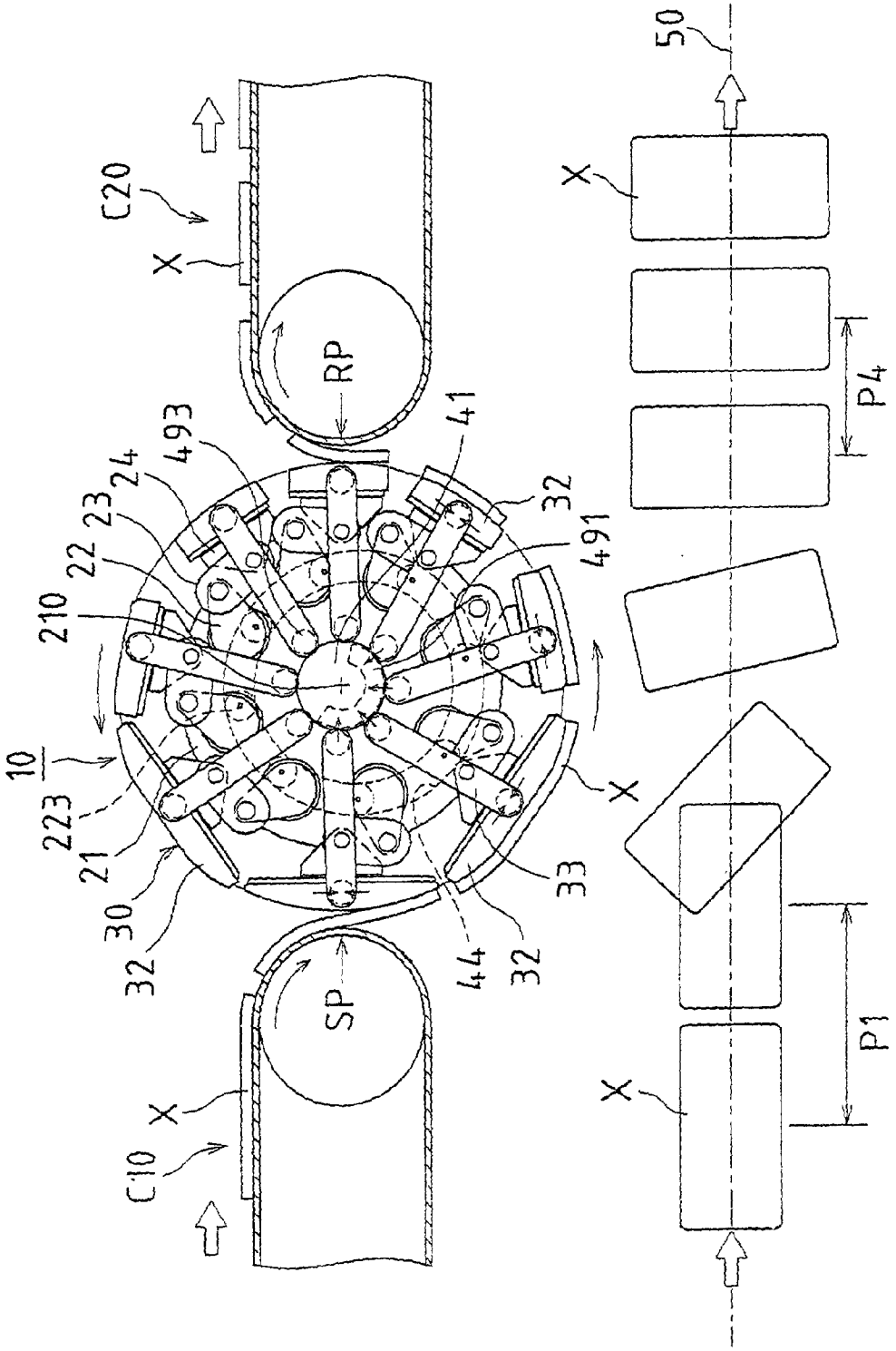
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FIG. 2

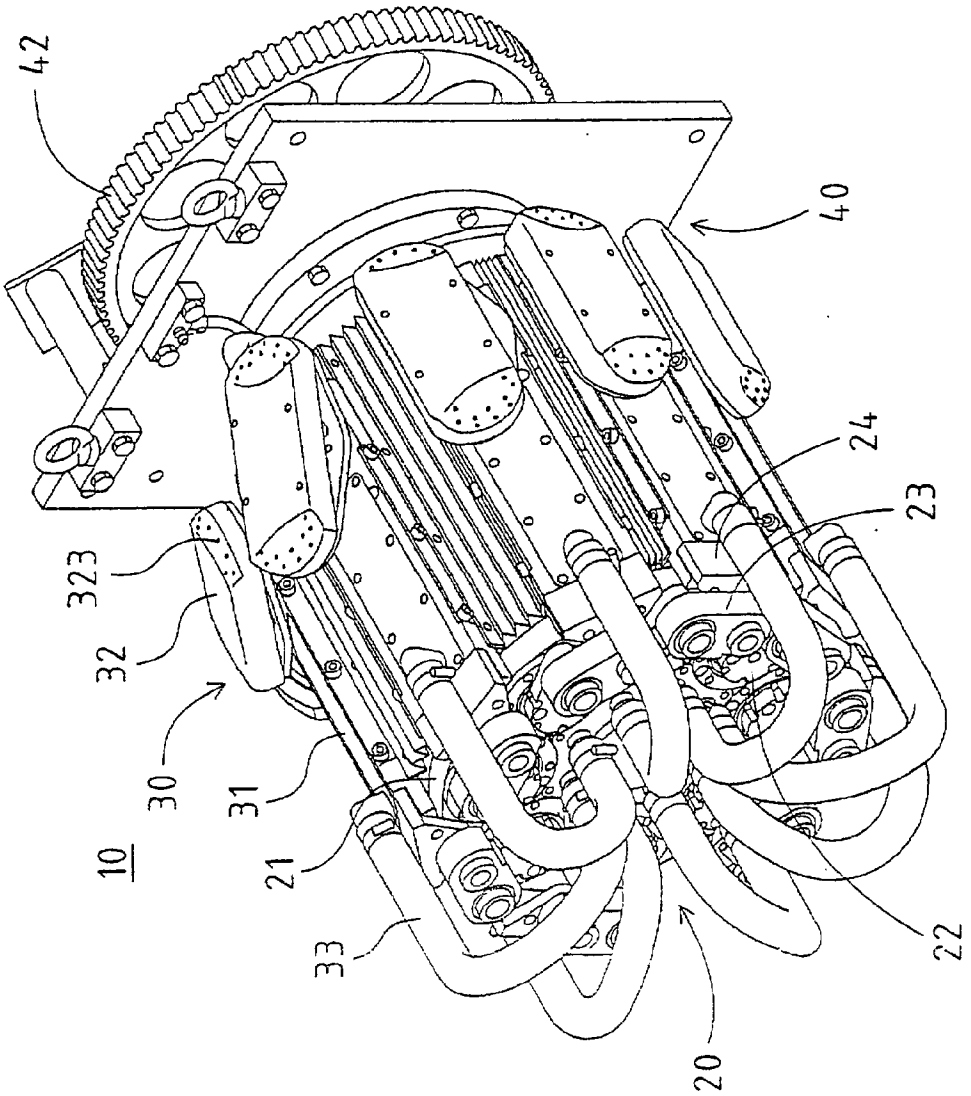

FIG. 3

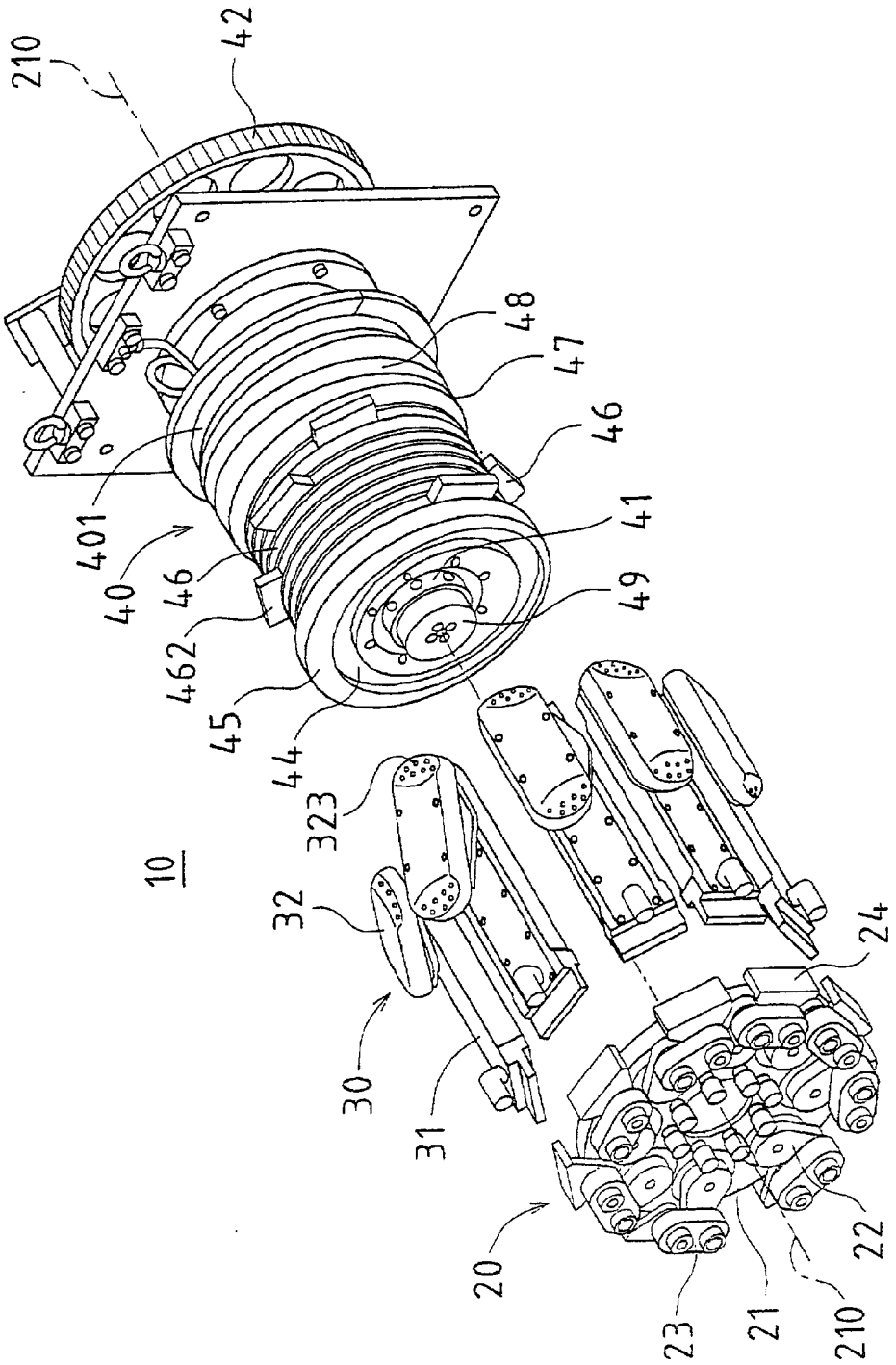
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FIG. 4

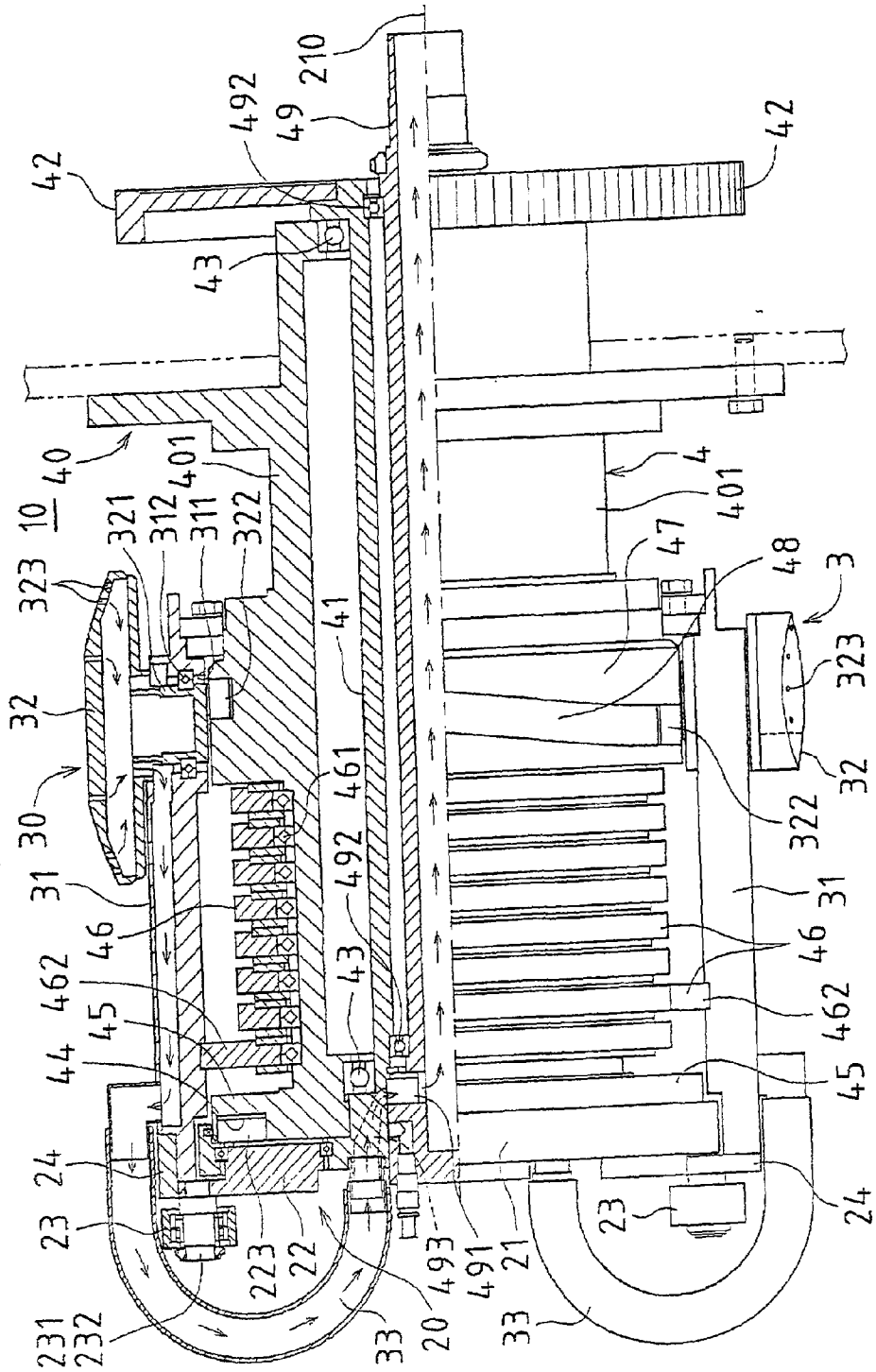
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FIG. 5

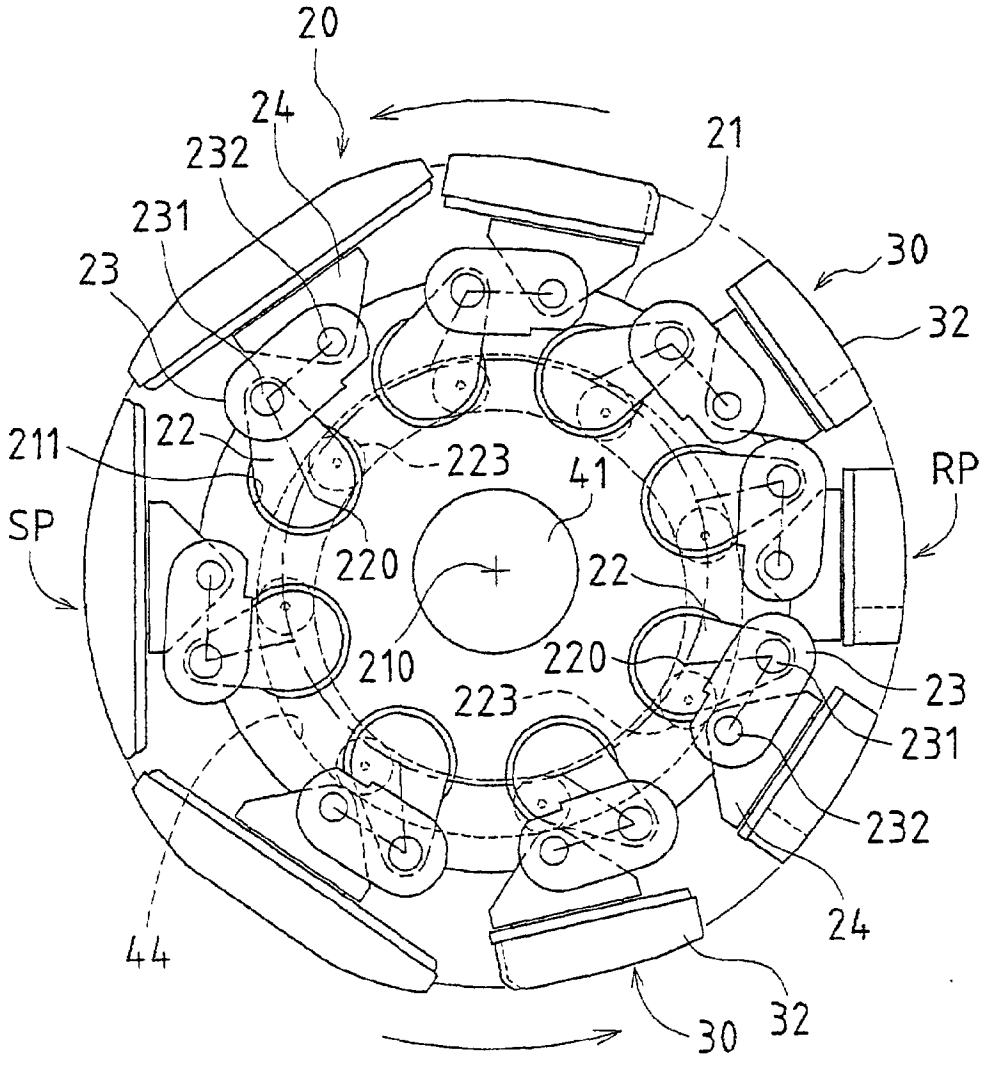
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FIG. 6

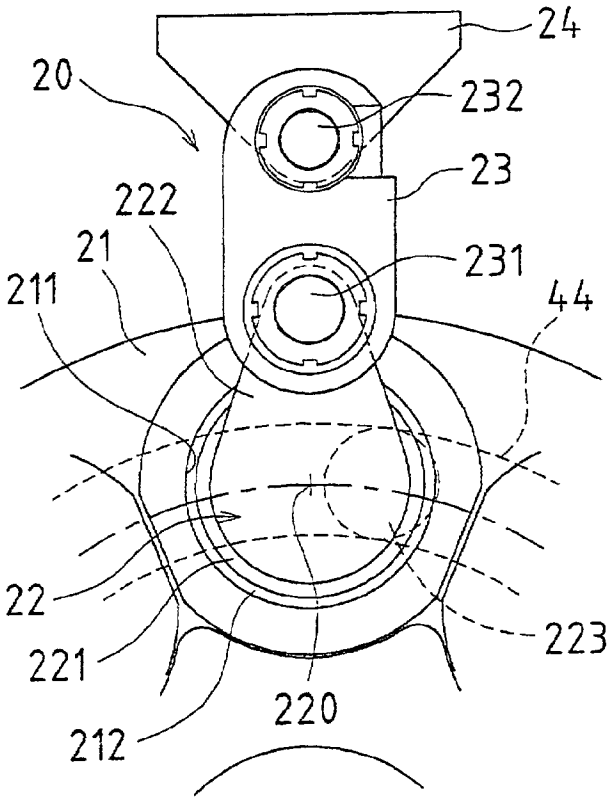

FIG. 7

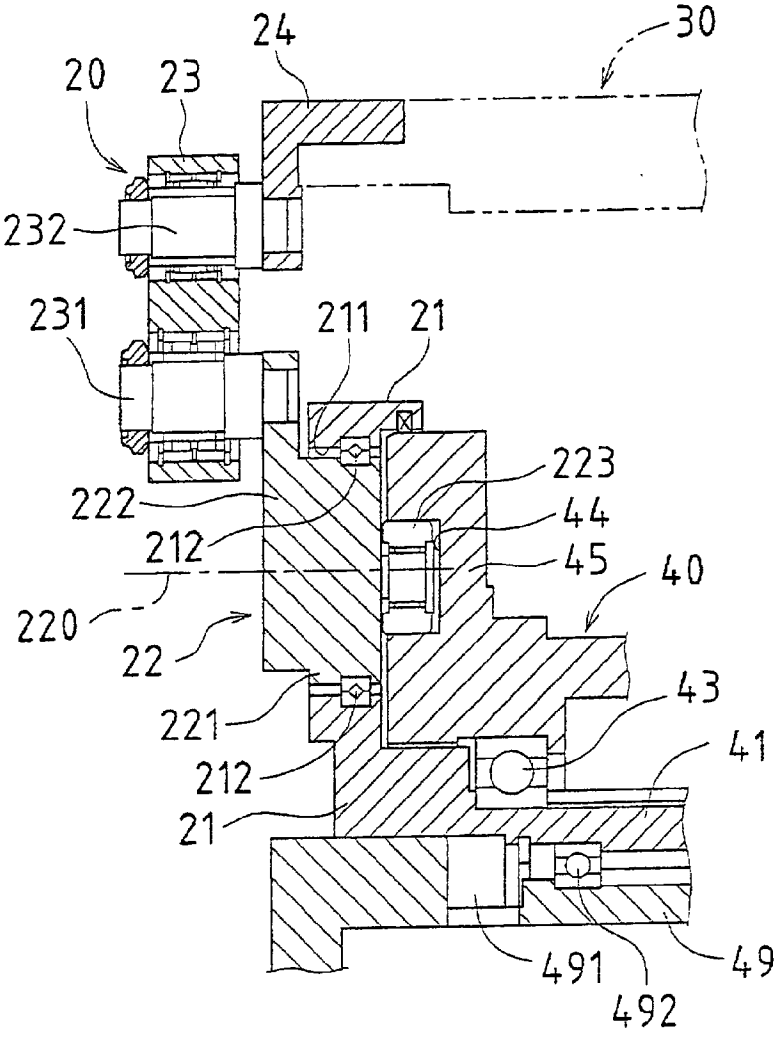
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FIG. 8

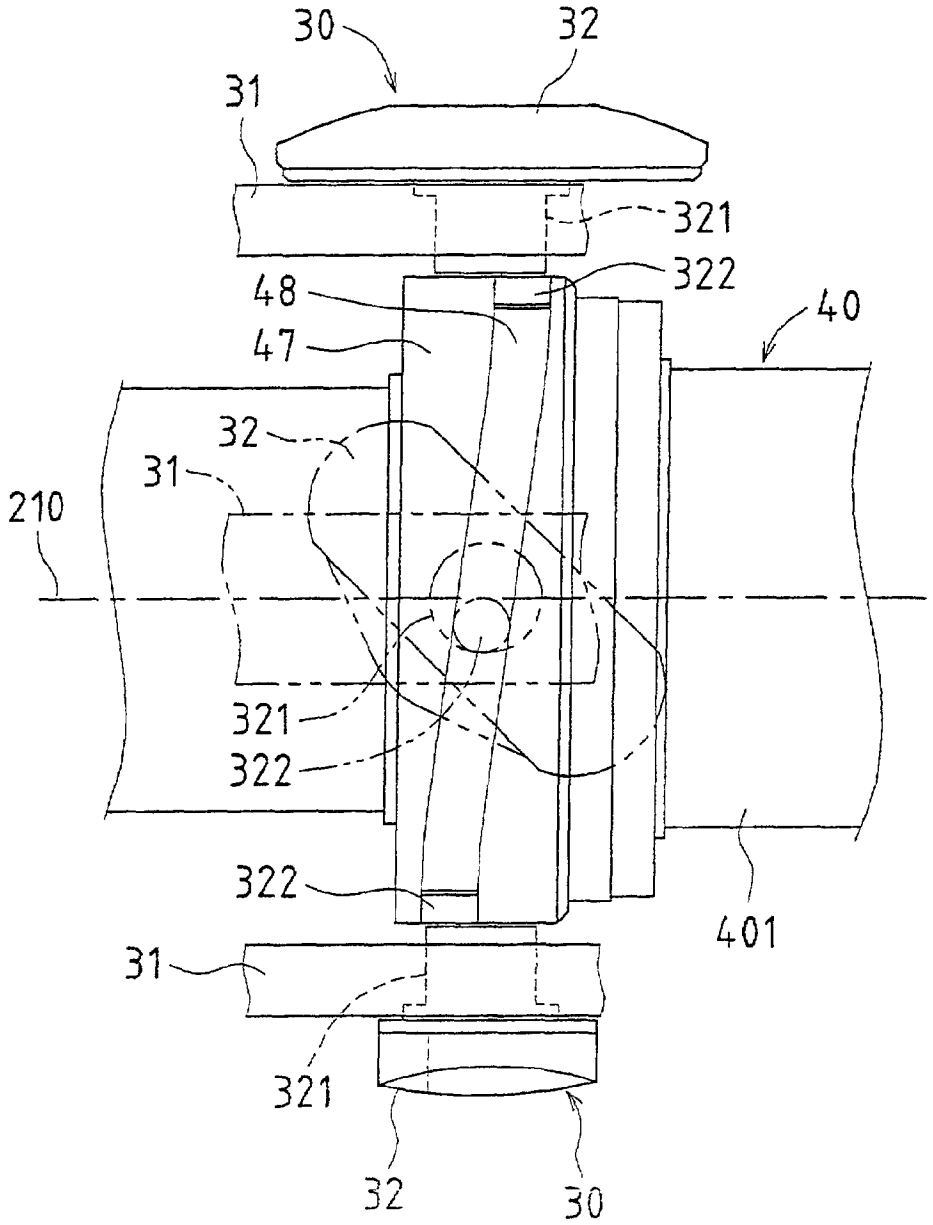

FIG. 9

INTERNATIONAL SEARCH REPORT

International application No.
PCT/JP00/08879

A. CLASSIFICATION OF SUBJECT MATTER
Int.Cl[7] B65G 47/86

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
Int.Cl[7] B65G 47/84-47/86

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched
Jitsuyo Shinan Koho 1926-1996 Jitsuyo Shinan Toroku Koho 1996-2001
Kokai Jitsuyo Shinan Koho 1971-2001 Toroku Jitsuyo Shinan Koho 1994-2001

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X Y	JP, 2-502626, A (Molnlycke AB), 23 August, 1990 (23.08.90) & SE, 8700279, A & NO, 880246, A & WO, 88005416, A & DK, 526088, A & US, 4880102, A & EP, 417068, A	1,3-7,9 2,8,10-12
Y	US, 5025910, A (Curt G. Joa, Inc.), 25 June, 1991 (25.06.91) & EP, 439897, A & CA, 2023816, A	2,8,10-12

☐ Further documents are listed in the continuation of Box C. ☐ See patent family annex.

* Special categories of cited documents:
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"O" document referring to an oral disclosure, use, exhibition or other means
"P" document published prior to the international filing date but later than the priority date claimed
"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"&" document member of the same patent family

Date of the actual completion of the international search	Date of mailing of the international search report
12 March, 2001 (12.03.01)	21 March, 2001 (21.03.01)
Name and mailing address of the ISA/ Japanese Patent Office	Authorized officer
Facsimile No.	Telephone No.

Form PCT/ISA/210 (second sheet) (July 1992)